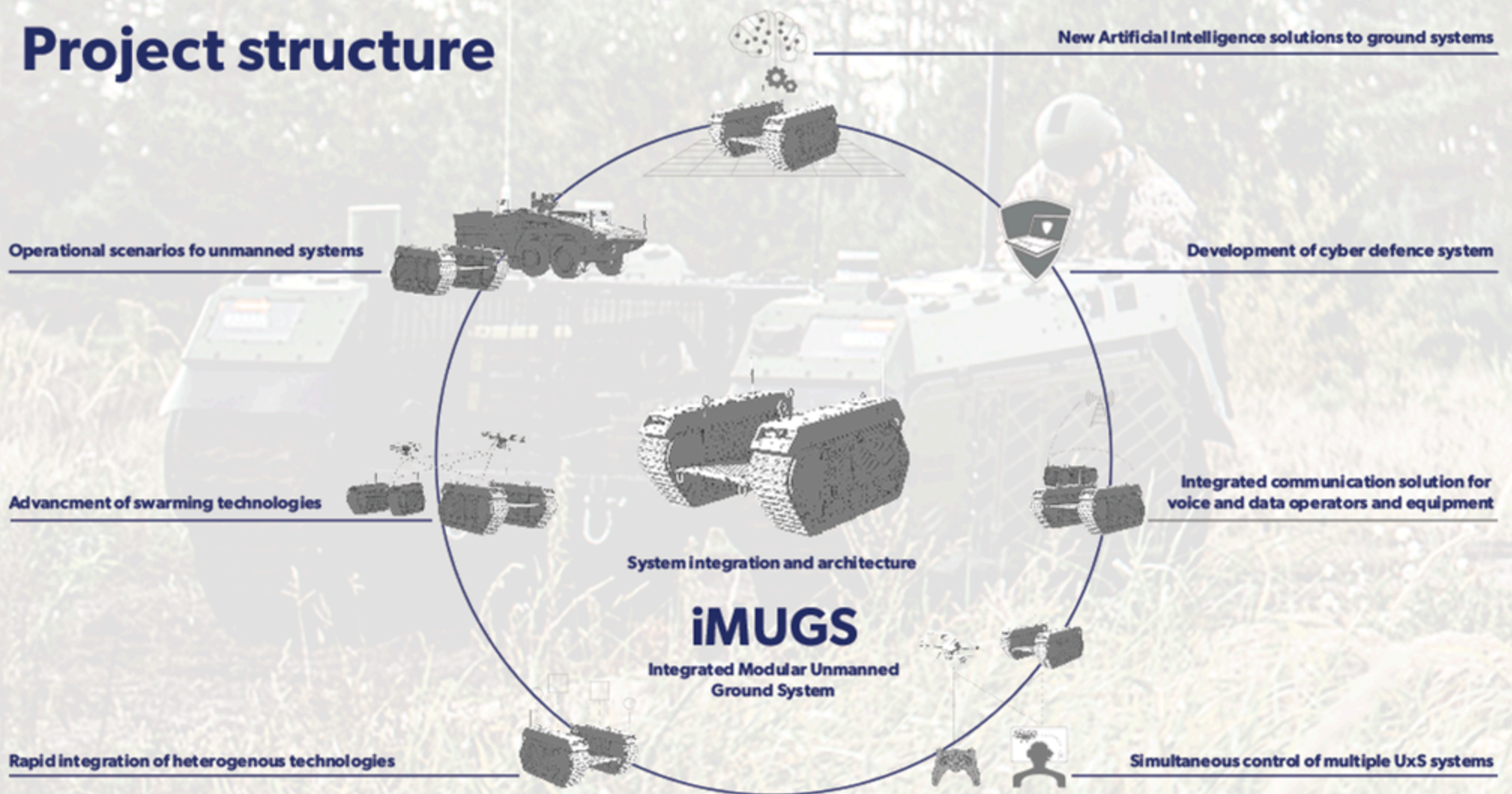




iMUGS

During the iMUGS program, a robust, safe, EW-resistant, multi-mission European-standard Unmanned Ground System was developed. It integrated secure communications and autonomous mobility software, enabling operators to safely control multiple land and air platforms simultaneously. The system was based on Milrem Robotics' TheMIS UGV and a defined set of payloads.

Project structure



Partners



Belgium



Estonia



Finland



France



Germany



Latvia



Spain